

Module-2

Three-Phase Transformer, Parallel Operation of Transformer and Autotransformer



Module-2

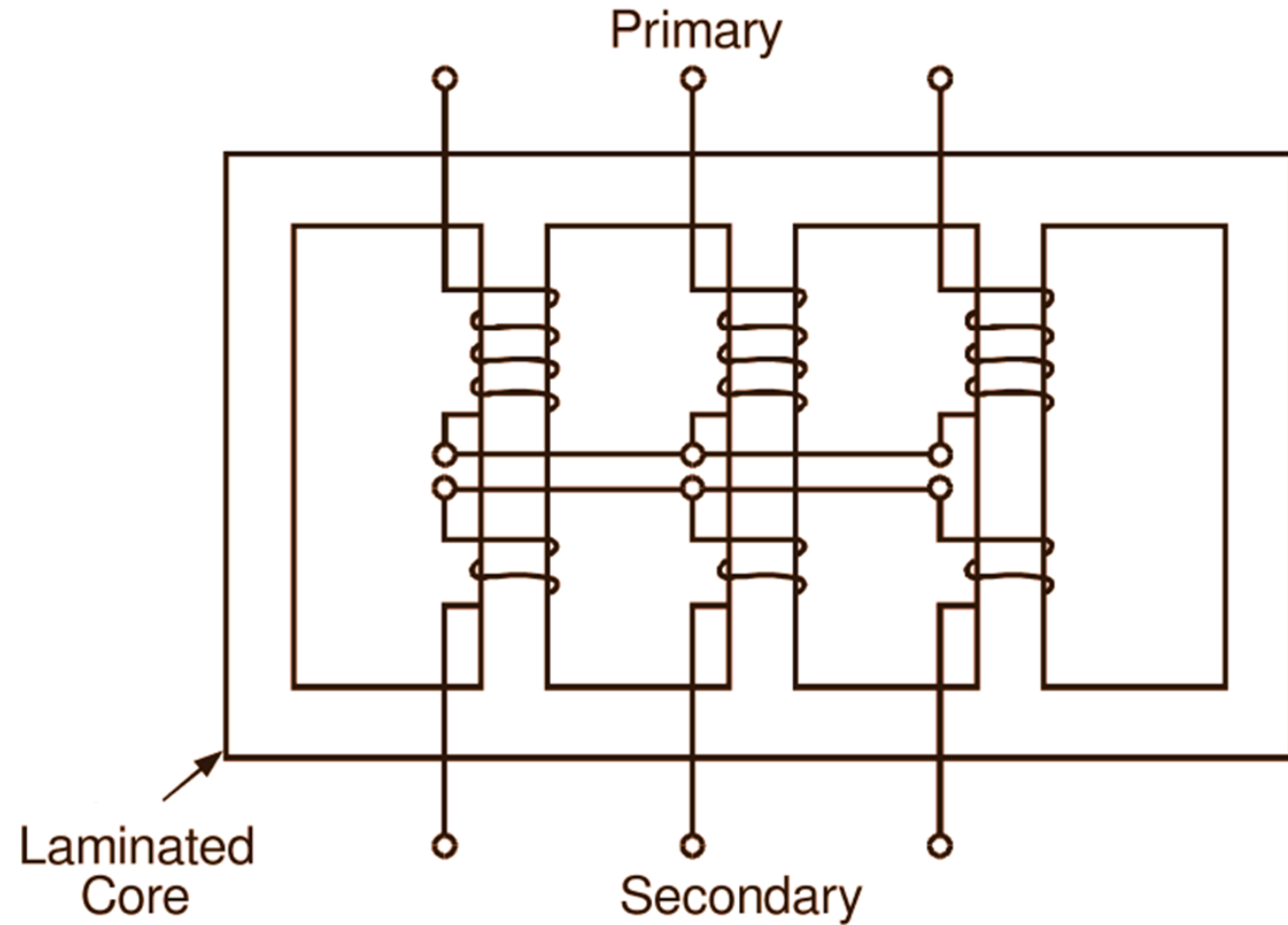
Three-phase Transformers: Introduction, Constructional features of three-phase transformers. Transformer connection for three-phase operation– star/star, delta/delta and star/delta, comparative features. Labeling of three-phase transformer terminals.

Parallel Operation of Transformers: Necessity of Parallel operation, conditions for parallel operation– Single phase and three phases. Load sharing in case of similar and dissimilar transformers. Numerical.

Autotransformers and Tap changing transformers: Introduction to autotransformer-copper economy, equivalent circuit, no load, and on-load tap changing transformers. Numerical.

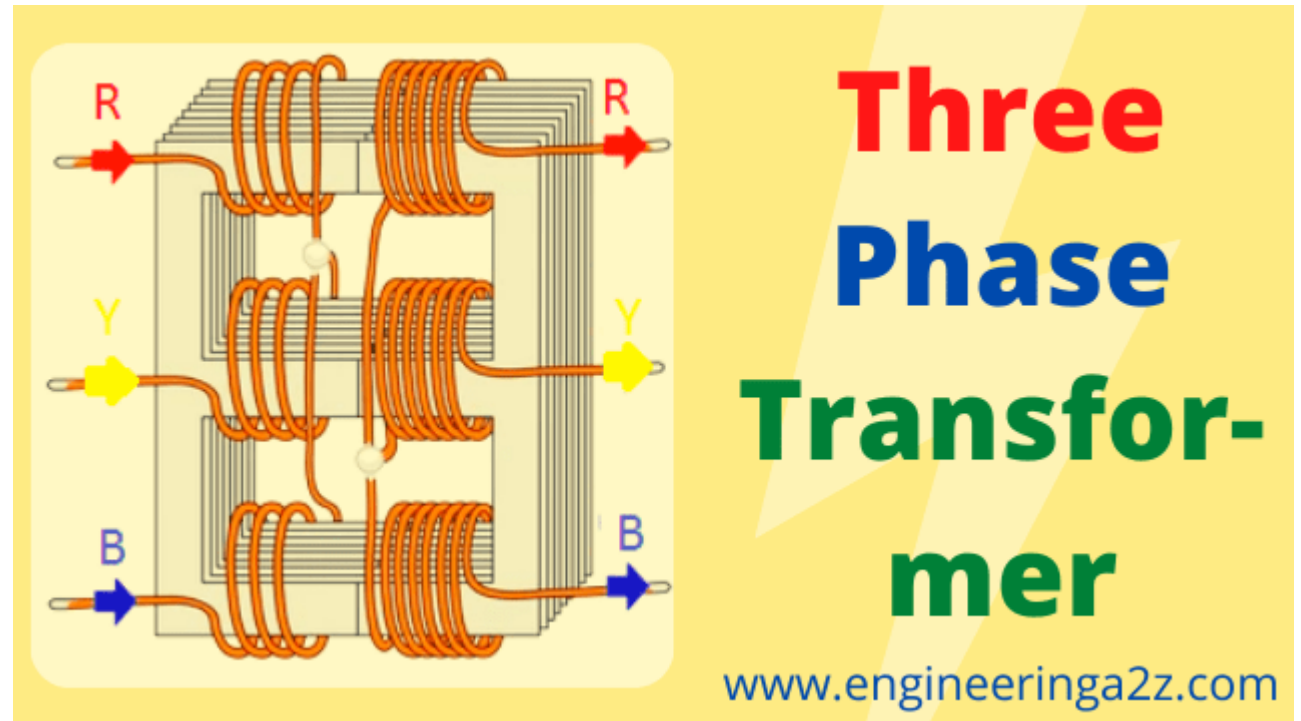
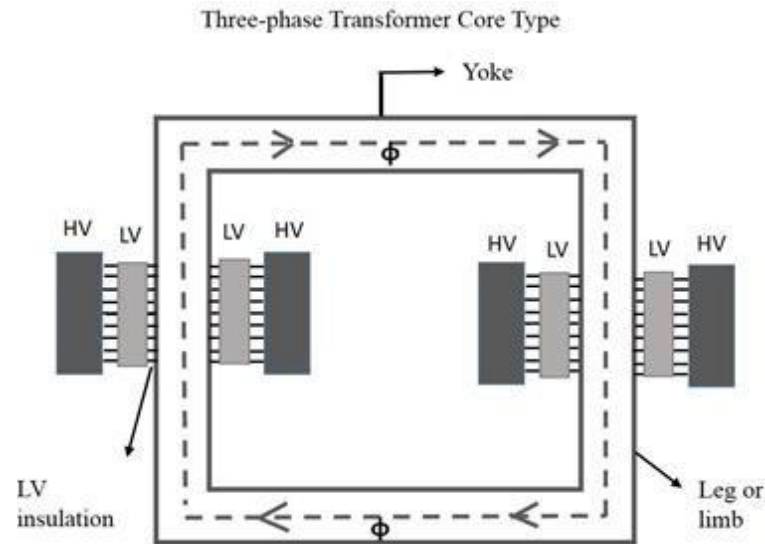
Constructional features of three-phase transformers:

Core Type Construction:

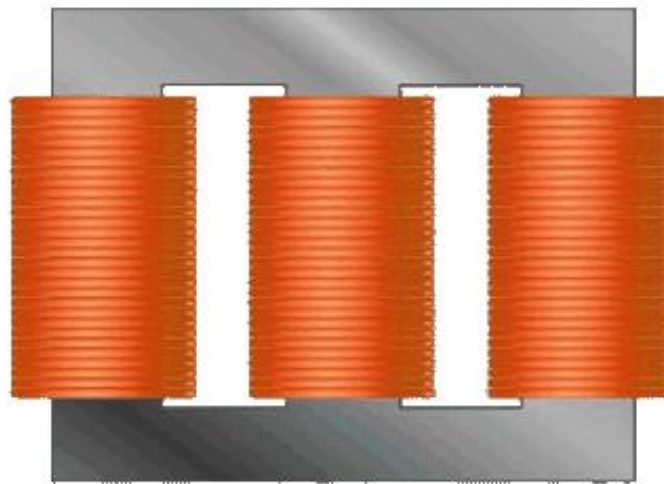


Constructional features of three-phase transformers:

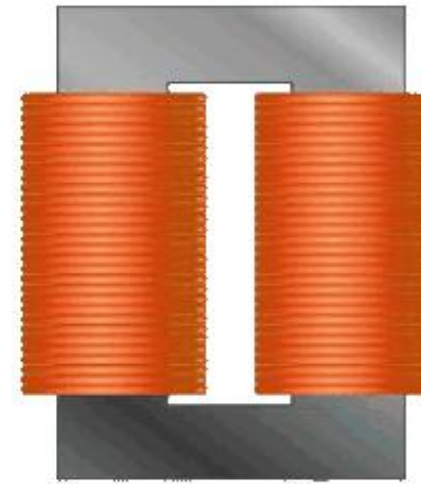
Core Type Transformer:



Core Type Transformer



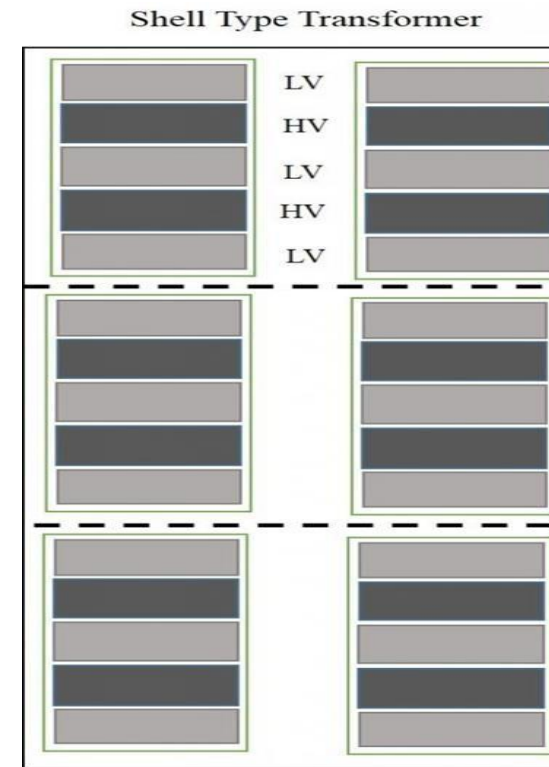
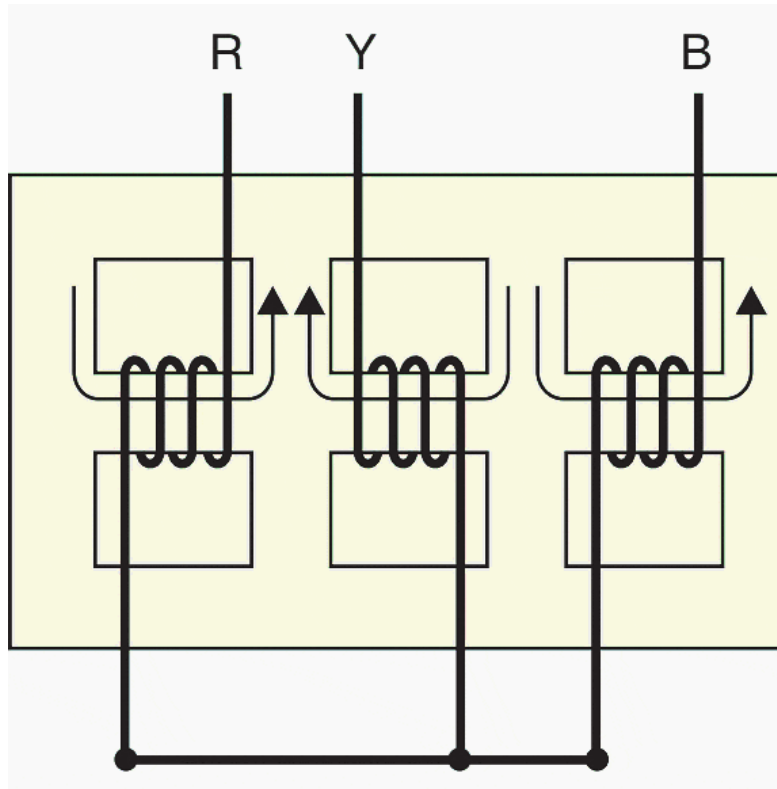
Three phase



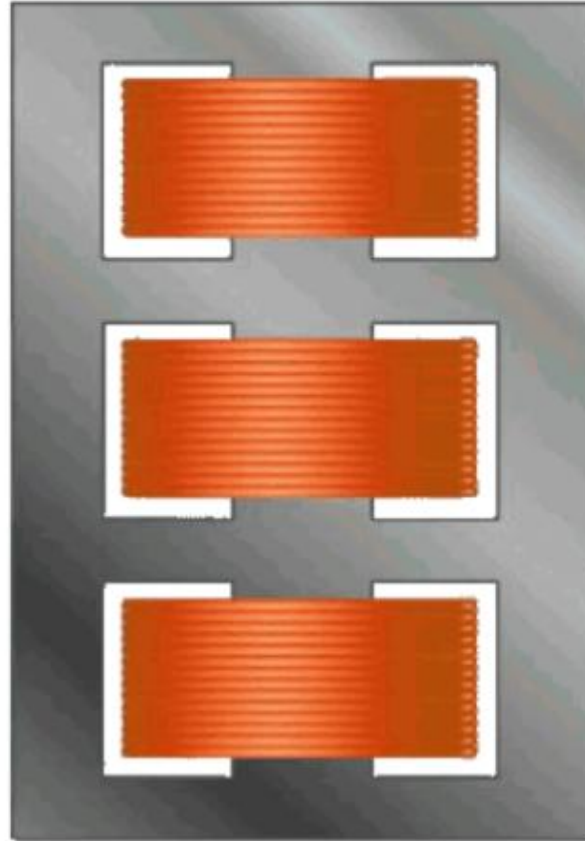
Single phase

Constructional features of three-phase transformers:

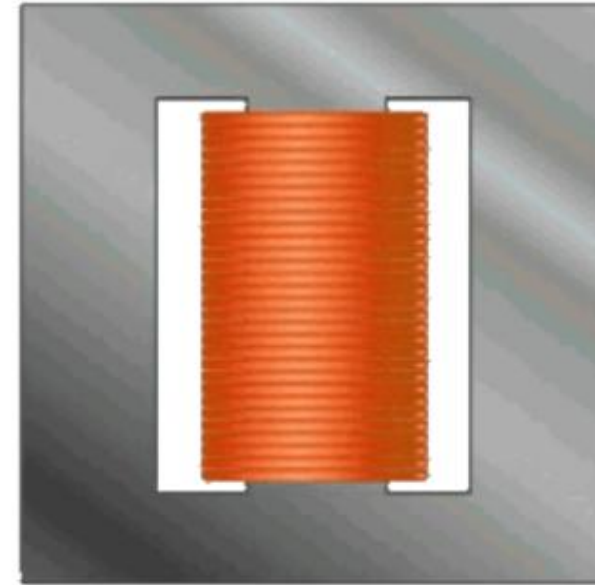
Shell Type Transformer:



Single Phase & Three Phase Transformer



Three phase

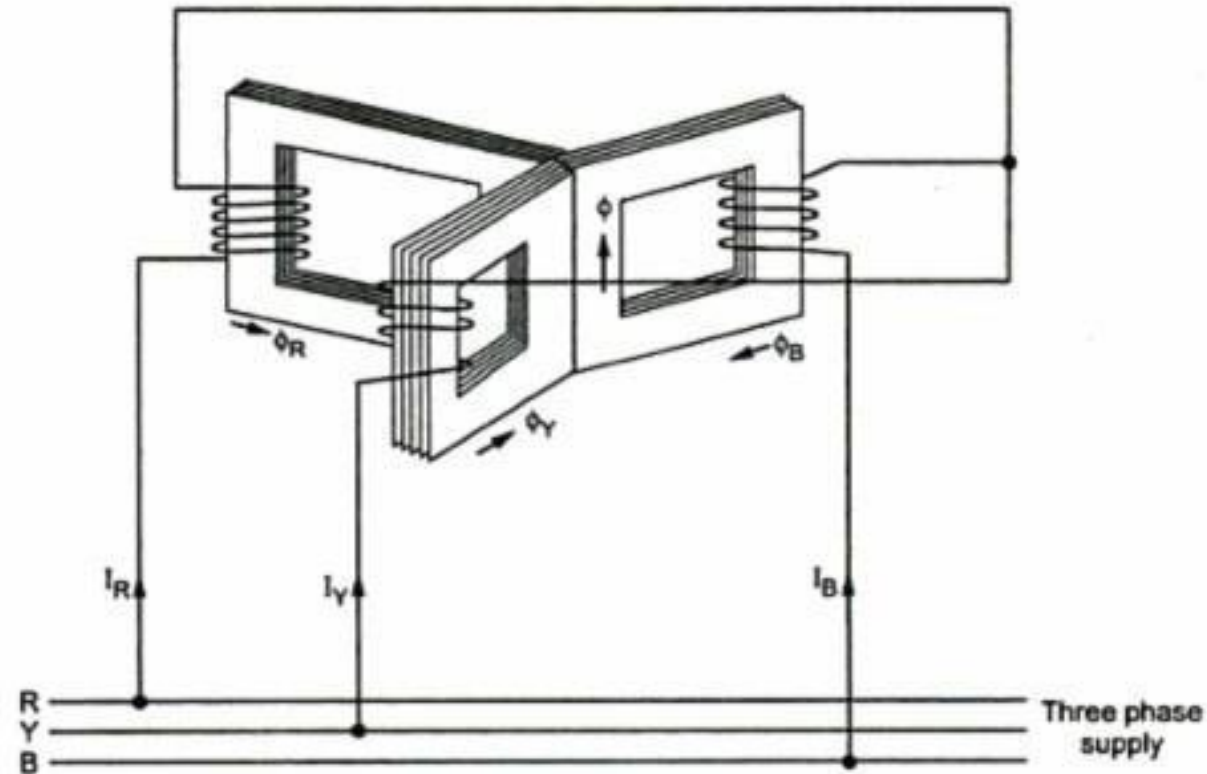


Single phase



ElectricalGang

Working of Three-Phase Transformers:

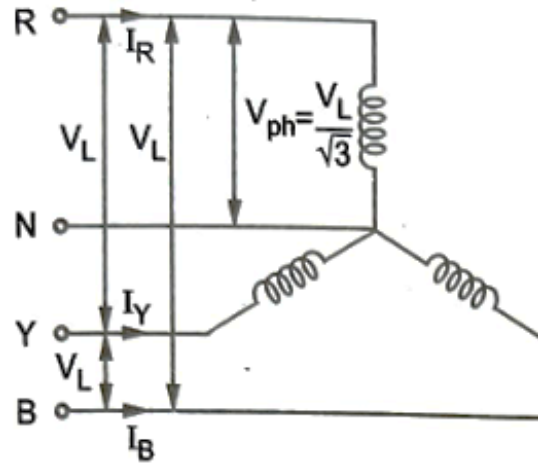


Three-Phase Transformer Connection:

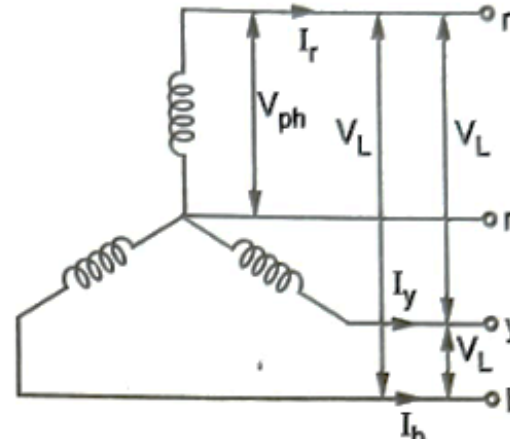
Primary and secondary windings of three phase transformers as three phase windings can be connected in different ways such as in star or delta.

1. Star-Star (Y-Y) connection 2. Delta – Delta (Δ - Δ) connection
3. Star-Delta (Y - Δ) connection 4. Delta-Star (Δ - Y) connection
5. Open Delta or V connection 6. Scott connection or T-T connection

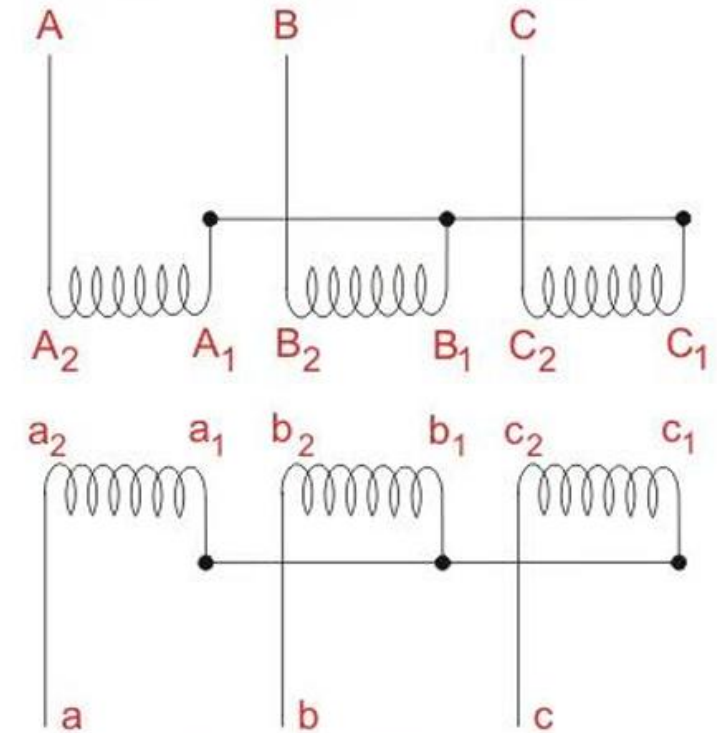
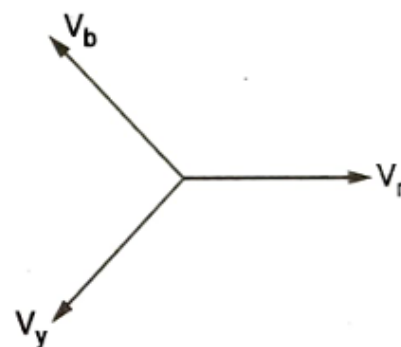
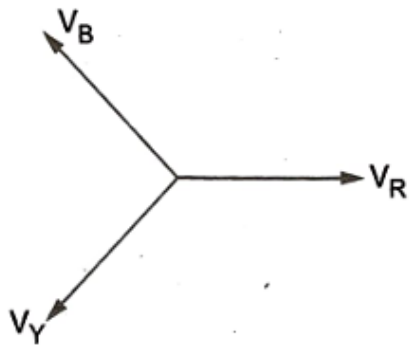
Star-Star Connection:



Primary side

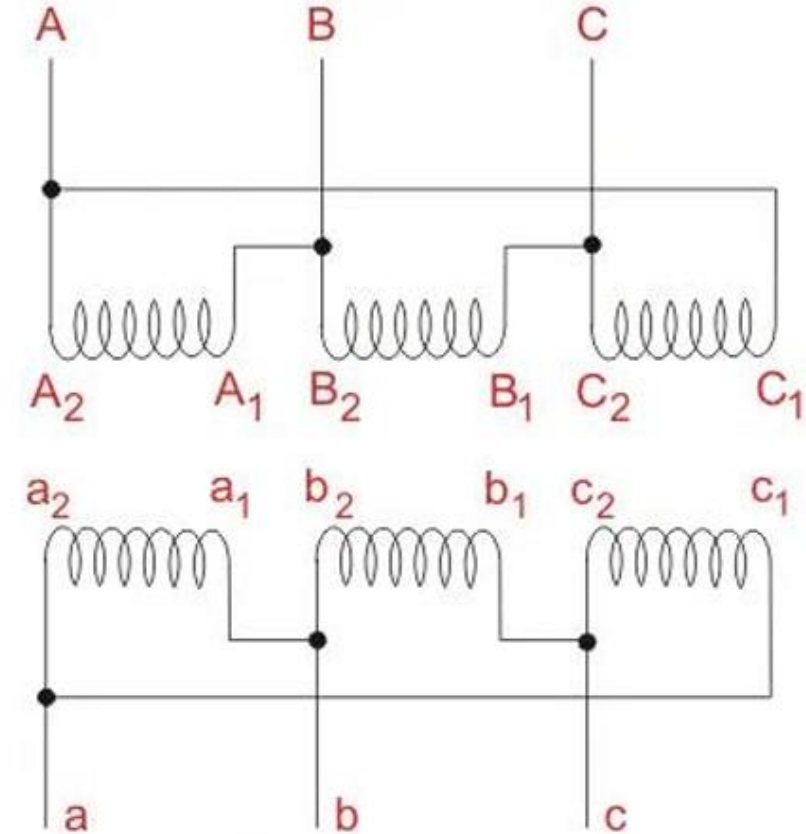
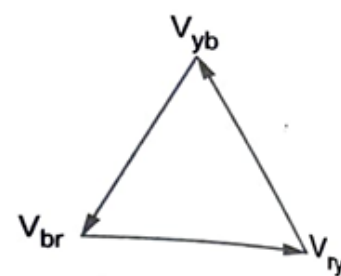
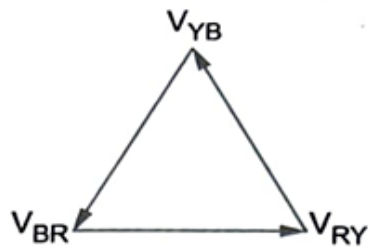
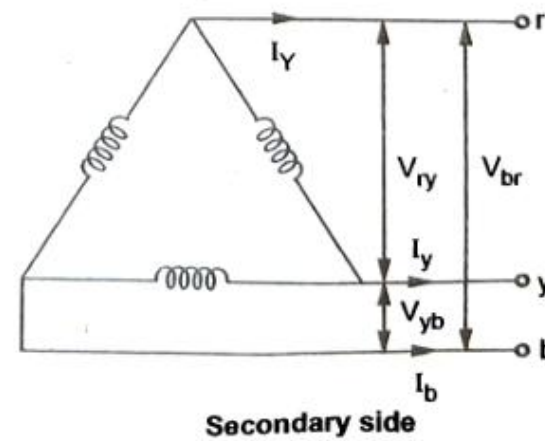
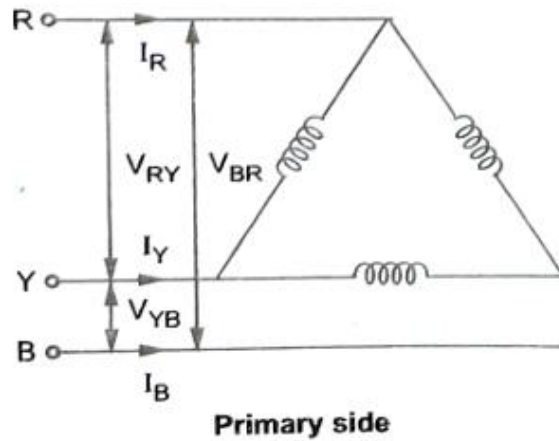


Secondary side



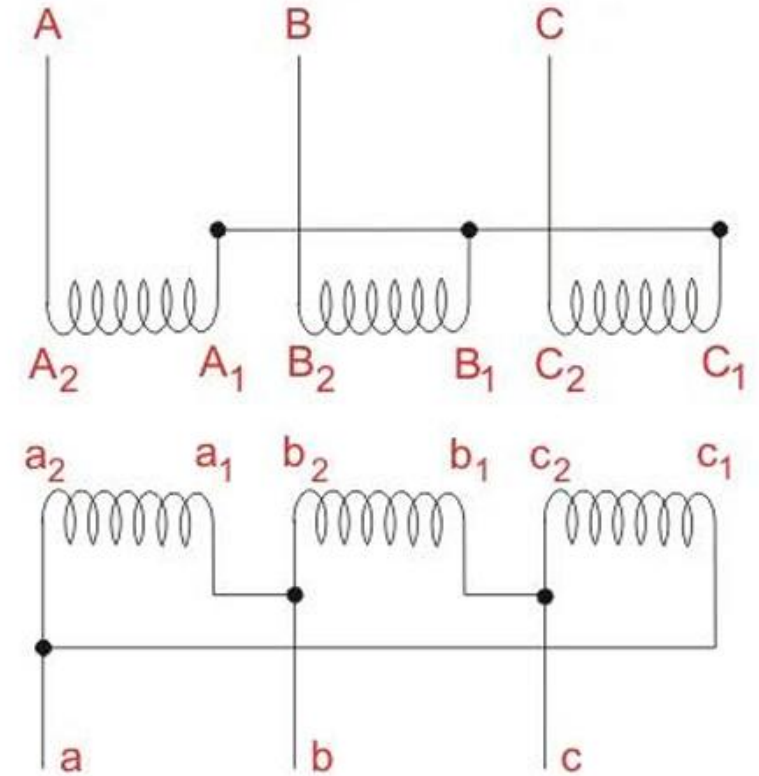
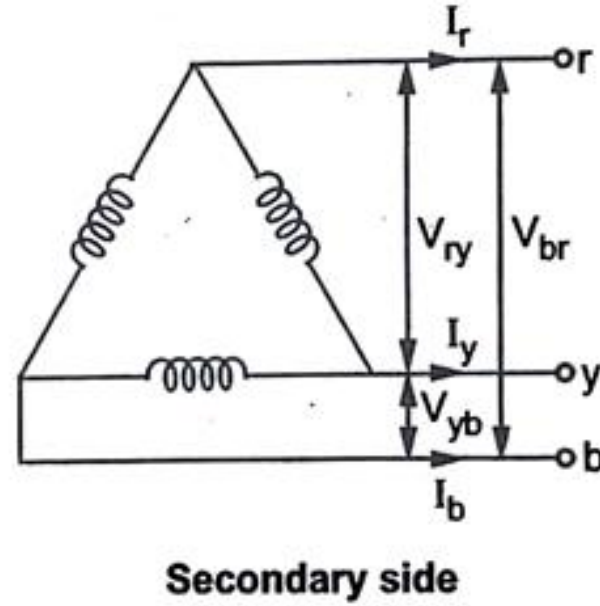
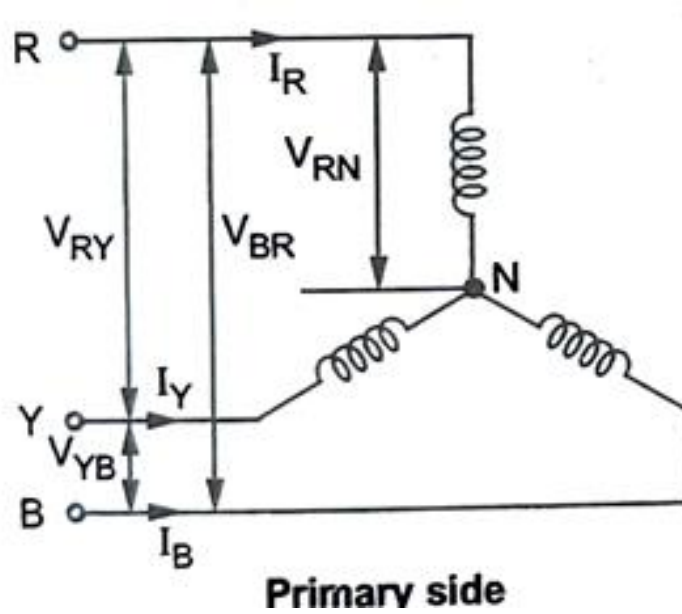
Star-Star Three Phase Transformer

Delta-Delta Connection:



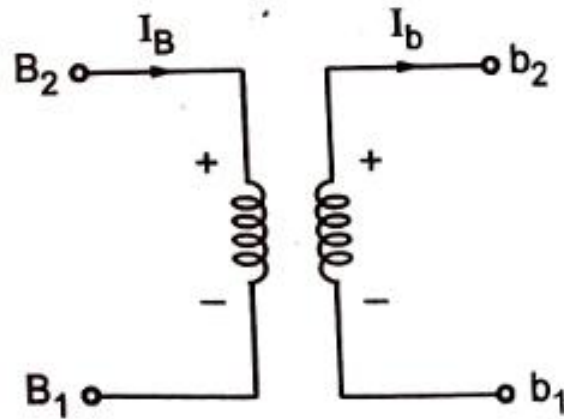
Delta-Delta Three Phase Transformer

Star-delta transformer:

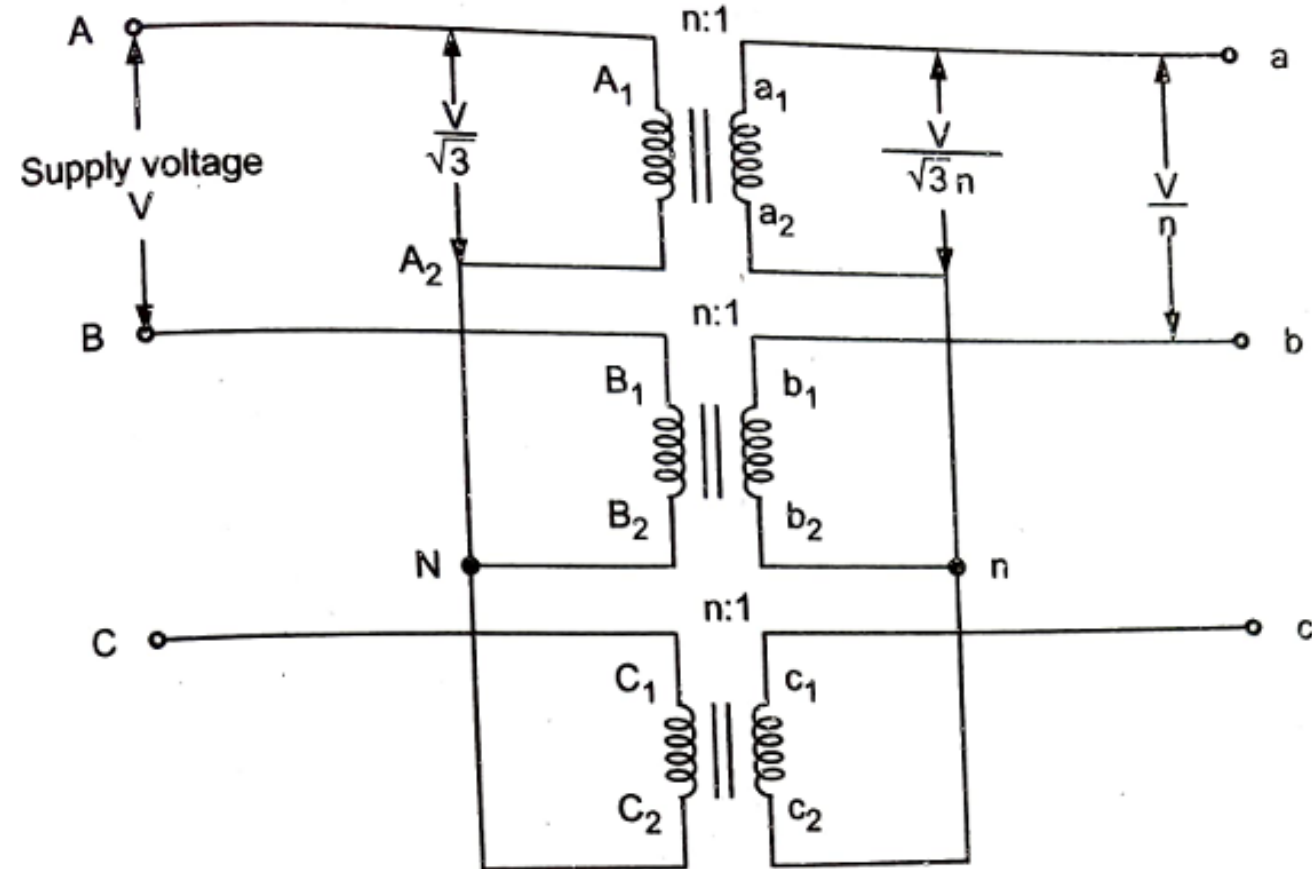


Star-Delta Three Phase Transformer

Labelling of Transformer:



Labelling of
transformer
terminals

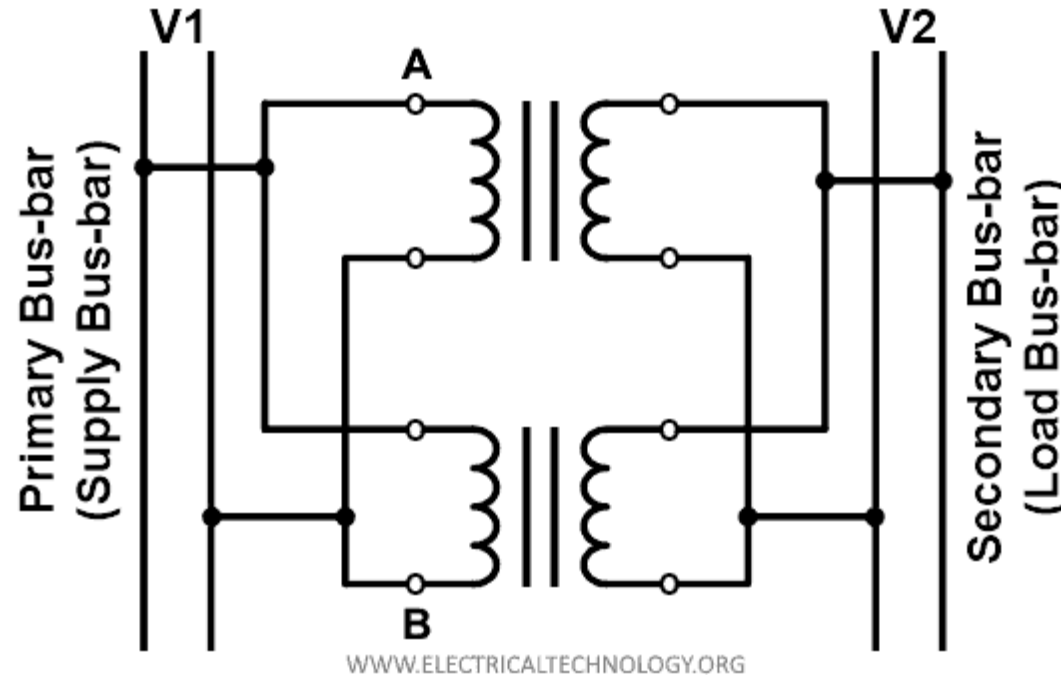


Comparative statement of star/star, delta/delta, and star/delta:

Type of connection	Primary Side			Secondary Side			
	Line voltage	Phase voltage	Phase Current	Phase Voltage	Phase Current	Line voltage	Line Current
Star-Star	V_L	$\frac{V_L}{\sqrt{3}}$	I_L	$\frac{KV_L}{\sqrt{3}}$	$\frac{I_L}{K}$	KV_L	$\frac{I_L}{K}$
Delta-Delta	V_L	V_L	$\frac{I_L}{\sqrt{3}}$	KV_L	$\frac{I_L}{K\sqrt{3}}$	KV_L	$\frac{I_L}{\sqrt{3}}$
Star-Delta	V_L	$\frac{V_L}{\sqrt{3}}$	I_L	$\frac{KV_L}{\sqrt{3}}$	$\frac{I_L}{K}$	$\frac{KV_L}{\sqrt{3}}$	$\frac{I_L}{\sqrt{3}}$
Delta-Star	V_L	V_L	$\frac{I_L}{\sqrt{3}}$	KV_L	$\frac{I_L}{K\sqrt{3}}$	$\sqrt{3}kv_L$	$\frac{I_L}{K\sqrt{3}}$

Parallel Operation of Transformers:

Parallel Operation of 1- Φ Transformers



Necessity of parallel operation:

1. When the load is **higher than** the ratings of the individual transformers parallel operation of smaller units **shares a high-capacity load**.
2. To make the power system **more reliable**, parallel operation is needed. If any one unit **develops a fault**, it can be removed and other units in parallel can maintain the supply.
3. According to the demand for power, the transformers in parallel can be **switched ON or OFF**. This reduces the transformer losses and makes the overall system **more efficient and economical**.
4. When the number Of transformers are connected in parallel, then the **cost of a standby unit is much less**.

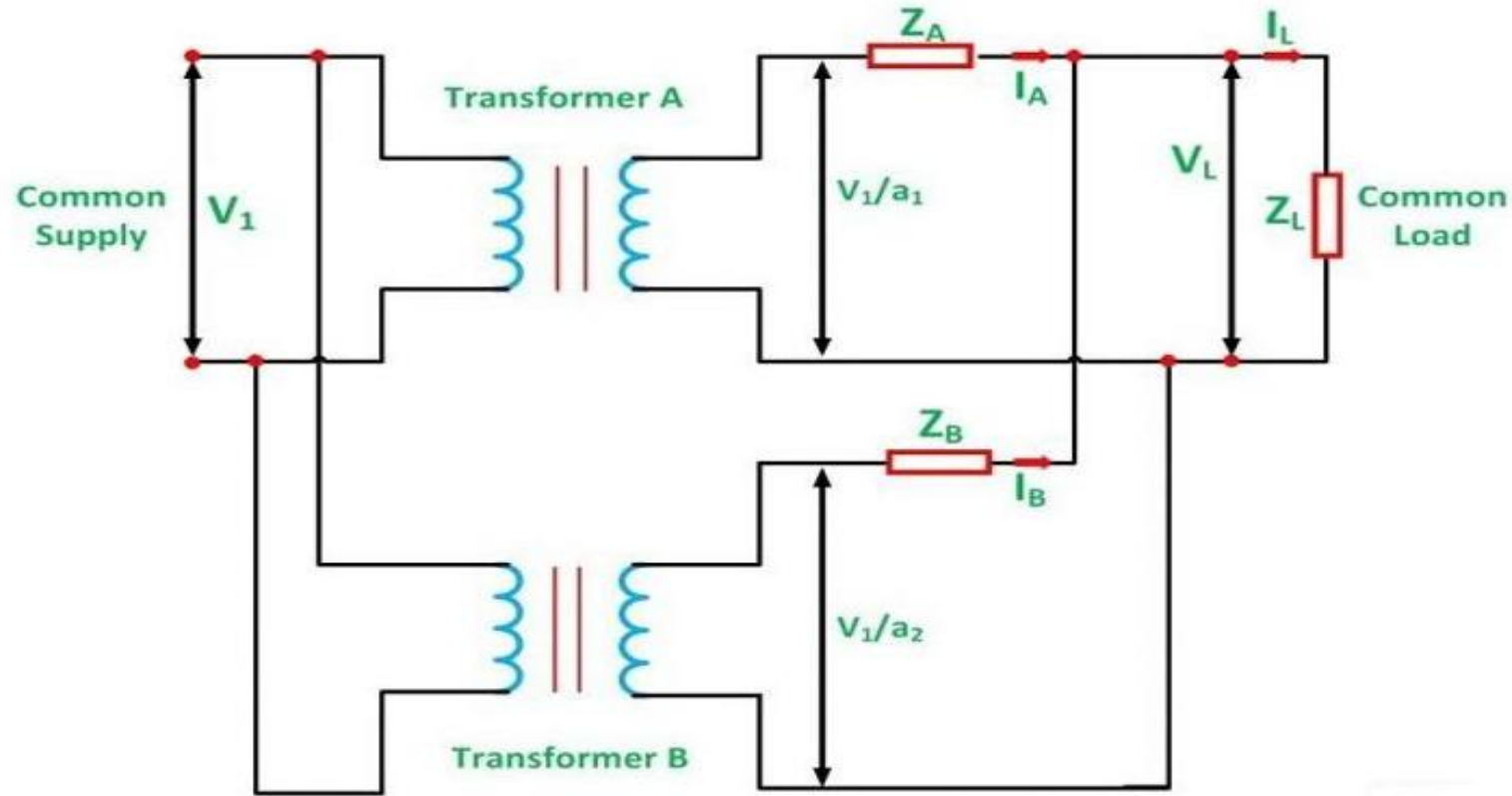
Advantages of using transformers in parallel:

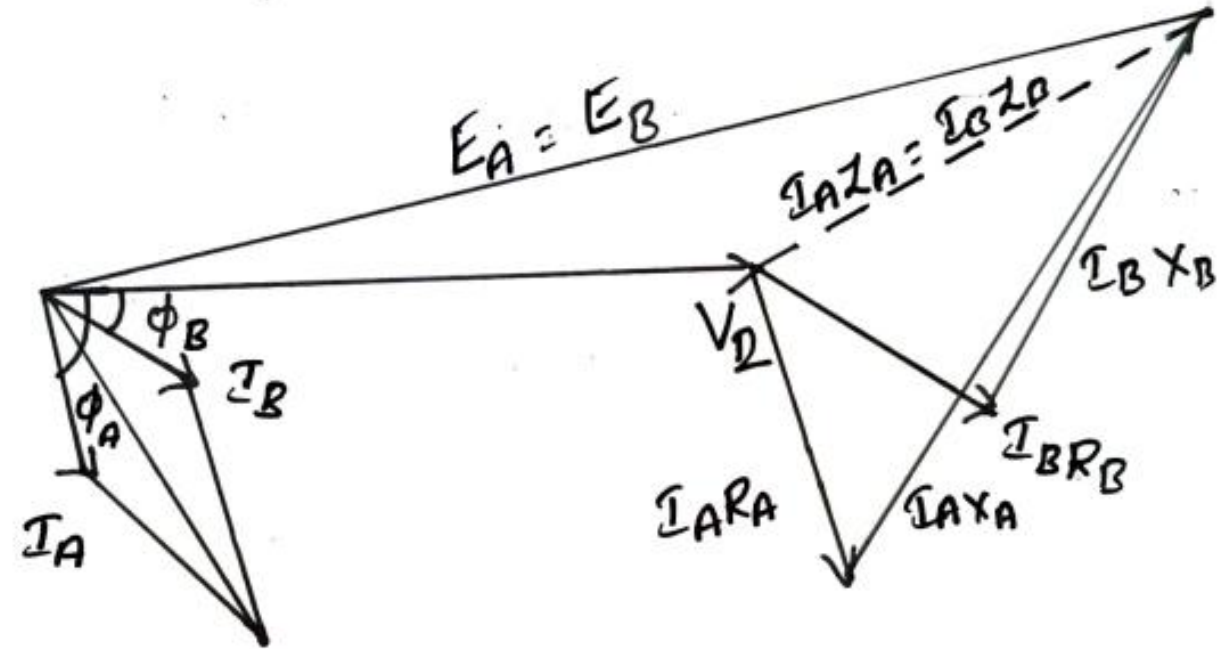
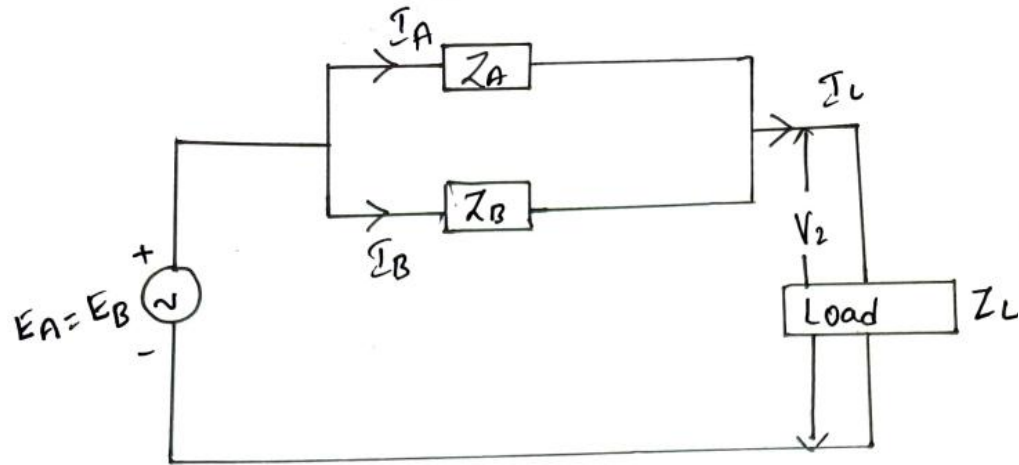
- ❖ To maximize electrical power system efficiency.
- ❖ To maximize electrical power system availability.
- ❖ To maximize power system reliability.
- ❖ To maximize electrical power system flexibility.

Conditions for parallel operation:

- ❖ The voltage ratio must be the same.
- ❖ The per unit impedance of each machine on its base must be the same.
- ❖ The polarity must be the same so that there is no circulating current between the transformers.
- ❖ The phase sequence must be the same and no phase difference must exist between the voltages of the two transformers.

Load sharing in case of similar transformers:





$$I_A + I_B = I_L \dots \dots \dots (1)$$

$$V_L = \frac{V_1}{a_1} - I_A Z_A \dots \dots \dots (2) \text{ and}$$

$$V_L = \frac{V_1}{a_2} - I_B Z_B \dots \dots \dots (3)$$

Now putting the value of I_B from the equation (1) in equation (3) we will get,

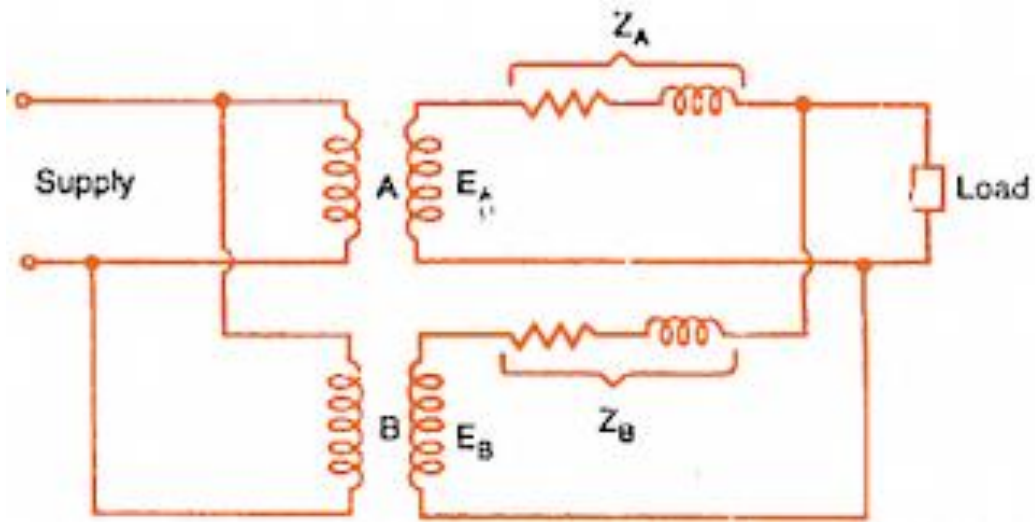
$$V_L = \frac{V_1}{a_2} - (I_L - I_A) Z_B \dots \dots \dots (4)$$

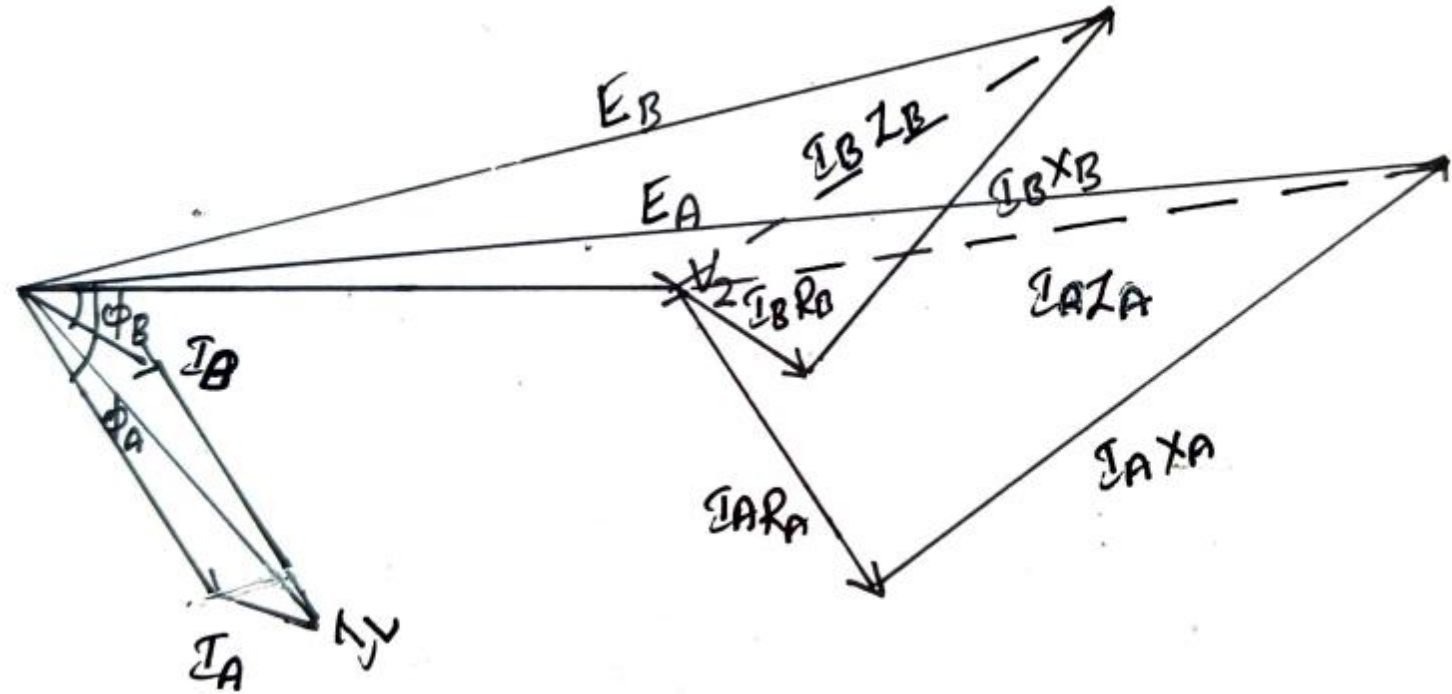
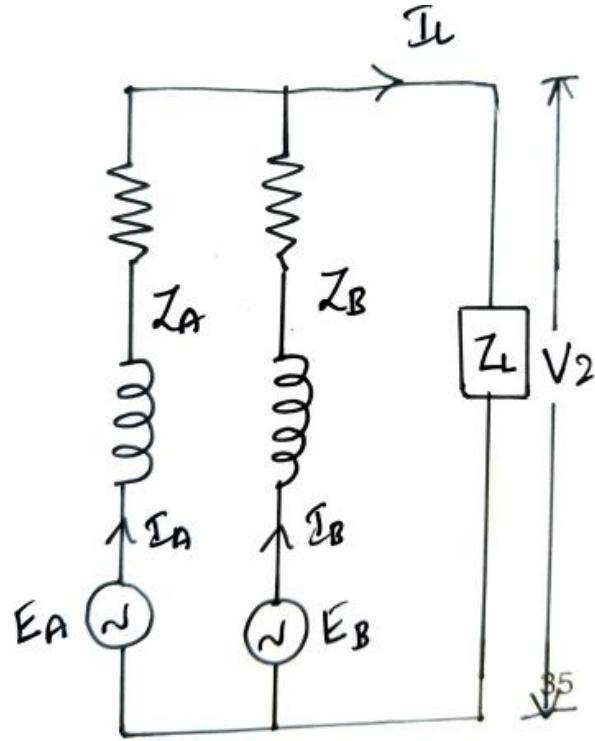
Solving equations (2) and (4) we will get,

$$I_A = \frac{Z_B I_L}{Z_A + Z_B} + \frac{V_1 (a_2 - a_1)}{a_1 a_2 (Z_A + Z_B)} \dots \dots \dots (5)$$

$$I_B = \frac{Z_A I_L}{Z_A + Z_B} + \frac{V_1 (a_2 - a_1)}{a_1 a_2 (Z_A + Z_B)} \dots \dots \dots (6)$$

Load sharing in case of dissimilar transformers:





$$I_C = \frac{E_A - E_B}{Z_A + Z_B}$$

$$E_A = V_2 + I_A Z_A ; E_B = V_2 + I_B Z_B \dots\dots\dots(1)$$

$$V_2 = I_L Z_L = (I_A + I_B) Z_L \dots\dots\dots(2)$$

$$E_A = (I_A + I_B) Z_L + I_A Z_A \dots\dots\dots(3)$$

$$E_B = (I_A + I_B) Z_L + I_B Z_B \dots\dots\dots(4)$$

Subtract (4) from (3)

$$E_A - E_B = I_A Z_A - I_B Z_B$$

$$I_A = \frac{(E_A - E_B) + I_B Z_B}{Z_A} \dots\dots\dots(5)$$

$$E_B = I_B Z_B + I_B Z_L + \left(\frac{(E_A - E_B) + I_B Z_B}{Z_A} \right) Z_L$$

$$E_B = I_B Z_B + I_B Z_L + \frac{(E_A - E_B) Z_L}{Z_A} + \frac{I_B Z_B Z_L}{Z_A}$$

$$E_B - \frac{(E_A - E_B) Z_L}{Z_A} = I_B Z_B + I_B Z_L + \frac{I_B Z_B Z_L}{Z_A}$$

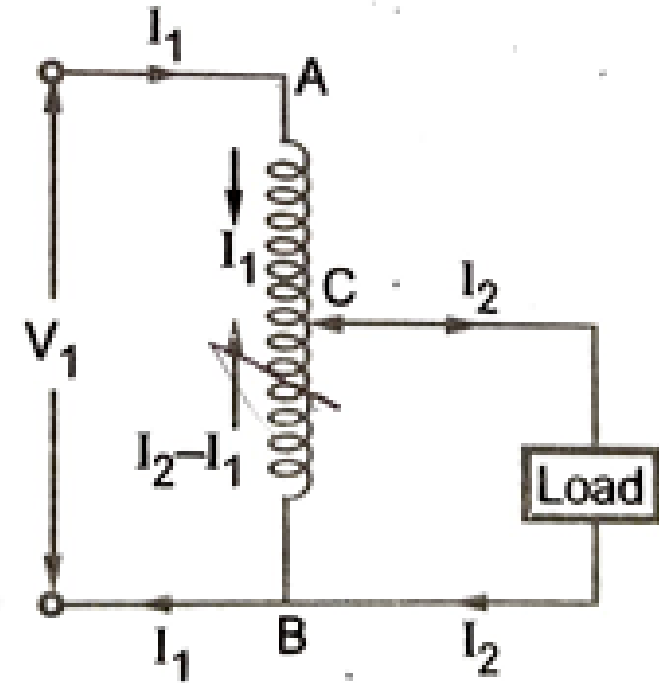
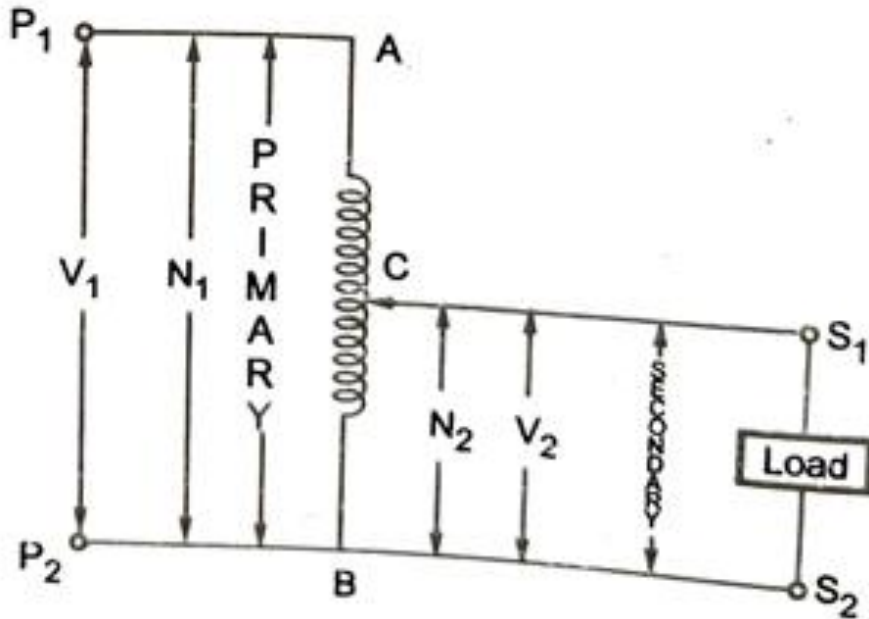
$$\frac{E_B Z_A - (E_A - E_B) Z_L}{Z_A} = I_B \left(\frac{Z_A Z_B + Z_A Z_L + Z_B Z_L}{Z_A} \right)$$

$$I_B = \frac{E_B Z_A - (E_A - E_B) Z_L}{Z_A Z_B + Z_A Z_L + Z_B Z_L} = \frac{E_B Z_A - (E_A - E_B) Z_L}{Z_A Z_B + Z_L (Z_A + Z_B)}$$

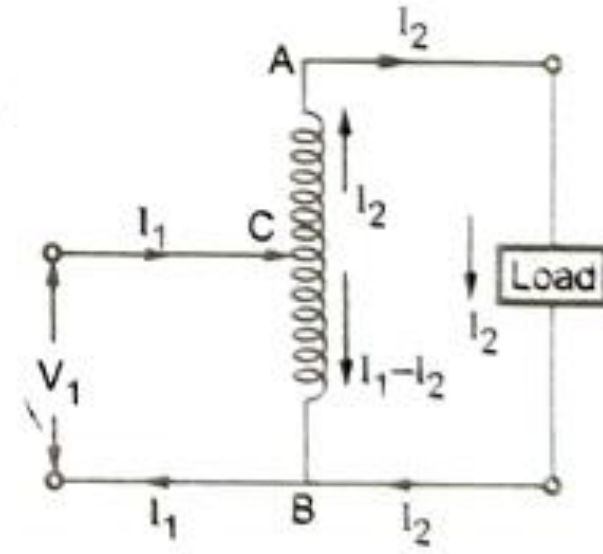
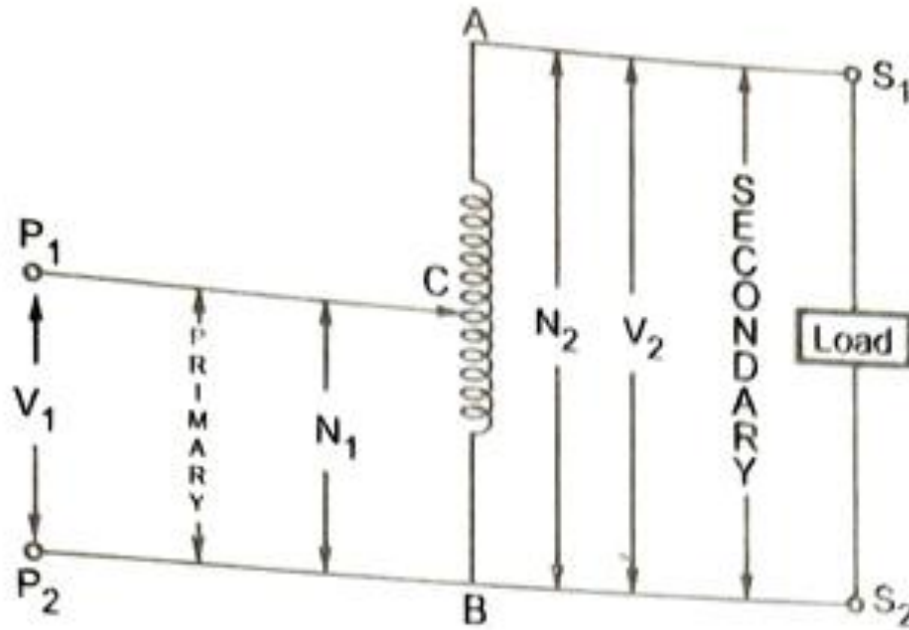
$$I_B = \frac{E_B Z_A - (E_A - E_B) Z_L}{Z_A Z_B + Z_L (Z_A + Z_B)}$$

$$I_A = \frac{E_A Z_B - (E_A - E_B) Z_L}{Z_A Z_B + Z_L (Z_A + Z_B)}$$

Construction of Autotransformers:

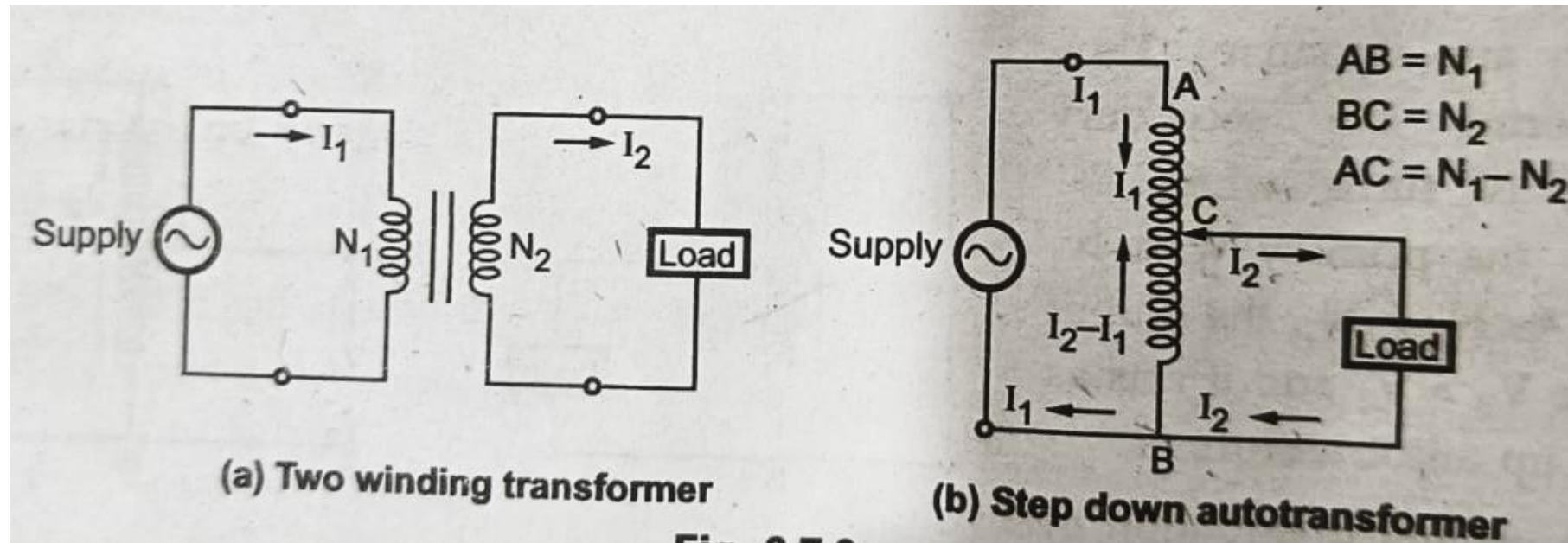


Step-down autotransformer



Step-up autotransformer

Saving of Copper in Auto Transformer as Compared to Ordinary Two-Winding Transformer:



Let W_{TW} = Total weight of copper in two winding transformers.

W_{AT} = Weight of copper in autotransformer

In two winding transformer,

Weight of copper of primary $\propto N_1 I_1$

Weight of copper of secondary $\propto N_2 I_2$

$W_{TW} \propto N_1 I_1 + N_2 I_2$ Total weight of copper

In case of step down autotransformer.

Weight of copper of section AC $\propto (N_1 - N_2)$

Weight of copper of section BC $\propto N_2 (I_2 - I_1)$

$W_{AT} \propto (N_1 - N_2) I_1 + N_2 (I_2 - I_1)$

Taking ratio of the weights,

$$\frac{W_{TW}}{W_{AT}} = \frac{N_1 I_1 + N_2 I_2}{(N_1 - N_2) I_1 + N_2 (I_2 - I_1)} = \frac{N_1 I_1 + N_2 I_2}{N_1 I_1 - N_2 I_1 + N_2 I_2 - N_2 I_1}$$

$$= \frac{N_1 I_1 + N_2 I_2}{N_1 I_1 + N_2 I_2 - 2 N_2 I_1}$$

But $K = \frac{N_2}{N_1} = \frac{I_1}{I_2}$

$$\frac{W_{TW}}{W_{AT}} = \frac{N_1 I_1 + K N_1 (I_1 / K)}{N_1 I_1 + K N_1 (I_1 / K) - 2 (K N_1) I_1} = \frac{2 N_1 I_1}{2 N_1 I_1 - 2 K N_1 I_1}$$

$$\frac{W_{TW}}{W_{AT}} = \frac{1}{1 - K}$$

$$W_{AT} = (1 - K) W_{TW}$$

Saving of copper = $W_{TW} - W_{AT} = W_{TW} - (1 - K) W_{TW}$

Saving of copper = $K W_{TW}$ For step down autotransformer

Thus saving in copper is K times the total weight of copper in two winding transformer.

Saving of copper = $\frac{1}{K} W_T$ For step up autotransformer

Advantages of Auto transformer:

- Copper required is very less.
- The efficiency is higher compared to two winding transformer.
- The size and hence cost is less compared to two winding transformer.
- The resistance and leakage reactance is less compared to two winding transformer
- The copper losses I^2R , are less.
- Due to less resistance and leakage reactance, the voltage regulation is superior than the two winding transformer.
- VA rating is more compared to two winding version.
- A smooth and continuous variation of voltage is possible.

Disadvantages of Auto transformer:

- Low impedance hence high short circuit currents for short circuits on secondary side.
- If a section of winding common to primary and secondary is opened, full primary voltage appears across the secondary resulting in higher voltages on secondary and danger of accidents.
- No electrical separation between primary and secondary which is risky in case of high voltage levels.
- Economical only where the voltage ratio is less than 2.

Applications of Auto transformer:

- It is used as a starter to give up to 50 to 60% of full voltage to the stator of a squirrel cage induction motor during starting.
- It is used to give a small boost to a distribution cable, to correct the voltage drop.
- It is also used as a voltage regulator
- Used in power transmission and distribution system and also in the audio system and railways.

Equivalent circuit of Autotransformer:

Consider an autotransformer as shown in the fig

R_1 and X_1 are the resistance and inductance of that part of the winding which carries only current I_1 .

R_2 and X_2 are the resistance and inductance of that part of the winding which behaves as secondary.

Applying Kirchhoff's law,

Applying Kirchhoff's law,

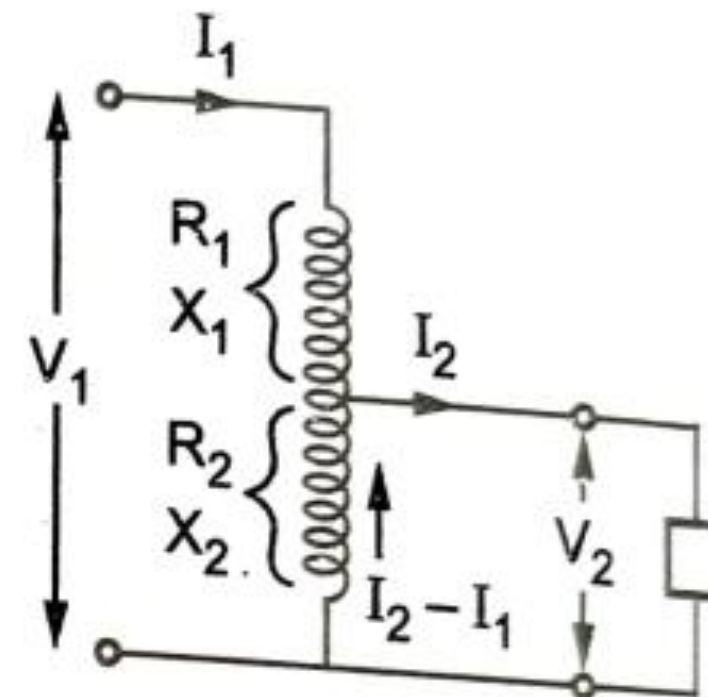
$$V_1 = E_1 + I_1(R_1 + jX_1) - (I_2 - I_1)(R_2 + jX_2) \quad \dots\dots\dots(1)$$

$$E_2 = V_2 + (I_2 - I_1)(R_2 + jX_2) \quad \dots\dots\dots(2)$$

$$K = \frac{V_2}{V_1} = \frac{E_2}{E_1} = \frac{I_2}{I_1} = \text{Transformation ratio}$$

$$E_1 = \frac{E_2}{K}, \quad I_2 = \frac{I_1}{K} \quad \text{and using in eqn(1)}$$

$$V_1 = \frac{E_2}{K} + I_1(R_1 + jX_1) + I_1(R_2 + jX_2) - \frac{I_1}{K}(R_2 + jX_2) \quad \dots\dots\dots(3)$$



Using equation (2) and (3)

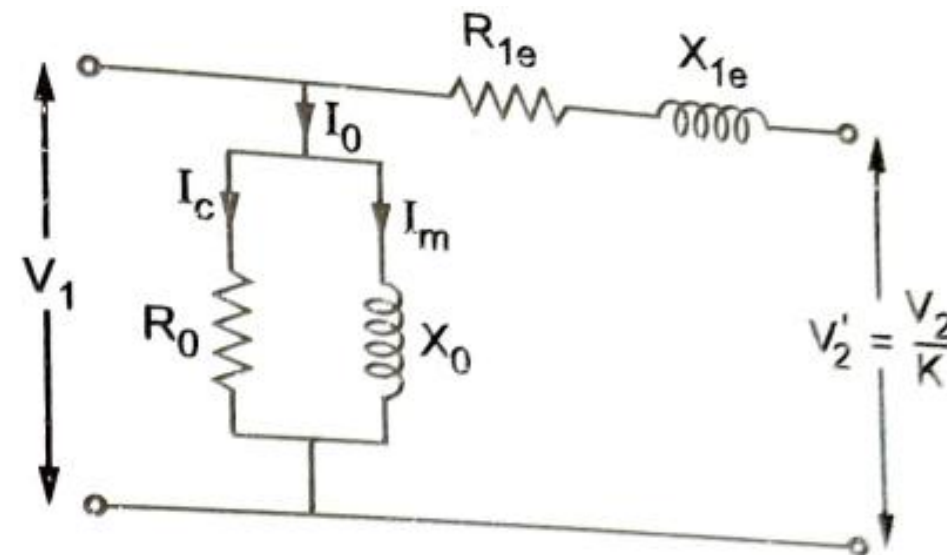
$$V_1 = \frac{V_2 + (I_2 - I_1)(R_2 + jX_2)}{K} + I_1(R_1 + jX_1) + I_1(R_2 + jX_2) - \frac{I_1}{K}(R_2 + jX_2)$$

$I_2 = \frac{I_1}{K}$ and combining the term of I_1 we get

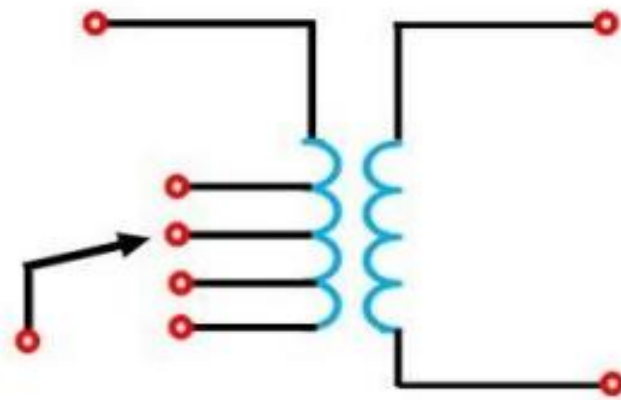
$$V_1 = \frac{V_2}{K} + I_1 \left\{ R_1 + R_2 \left(\frac{1}{K^2} - \frac{2}{K} + 1 \right) + j \left[X_1 + X_2 \left(\frac{1}{K^2} - \frac{2}{K} + 1 \right) \right] \right\}$$

$$V_1 = \frac{V_2}{K} + I_1 \left\{ R_1 + R_2 \left(\frac{1}{K} - 1 \right)^2 + j \left[X_1 + X_2 \left(\frac{1}{K} - 1 \right)^2 \right] \right\}$$

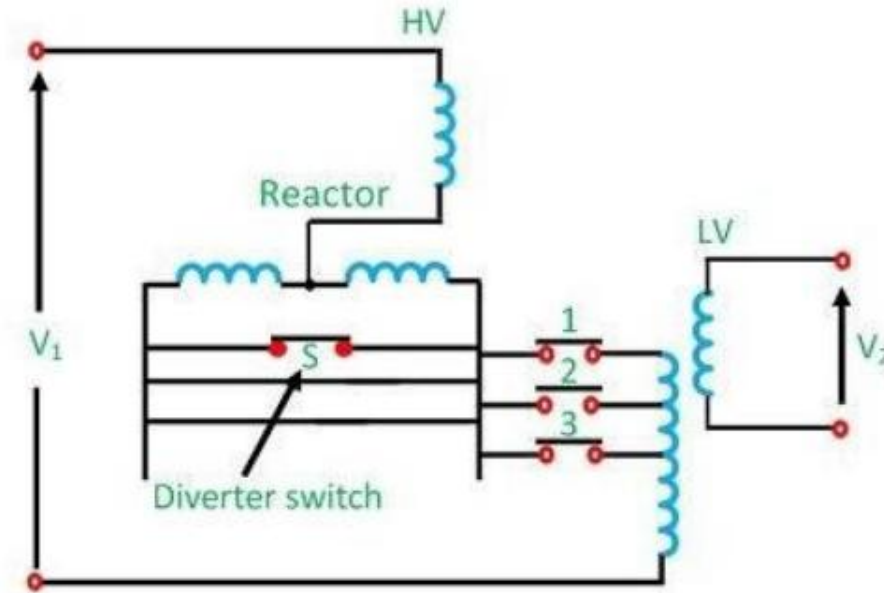
$$V_1 = V_2' + I_1 R_{1e} + I_1 X_{1e} \quad \dots\dots\dots(4)$$



Tap-changing Transformers:



Off-load tap-changing transformer



On-load tap changing using a reactor

